

► ABSOLUTE ENCODERS WITH FIELDBUS INTERFACE

► MEM440-BUS



► MEM620-BUS

► MEM540-BUS

► MEM520-BUS

► MEM450-BUS



► ORDERING INFORMATION

[] MEM520B = Round flange Ø 58 mm SYNCHRO FLANGE

[] MEM440B = Blind hollow shaft for motor coupling

[] MEM450B = Blind hollow shaft, fixing by elastic support



TYPE

INTERFACE

ECT = EtherCAT



NO. OF TURNS

M = Multiturn



SHAFT/HOLLOW SHAFT Ø

6 mm

[] 8 mm

[] 10 mm

[] 12 mm

[] 14 mm

[] 15 mm



CONNECTORS POSITION

Radial

[] Axial













▶ ELECTRICAL & OPERATING SPECIFICATIONS

Operating principle	Magnetic
Resolution/revolution	8192 steps/rev – 13 bit
Revolutions no.	65536 - 16 bit
Initializing time	< 1s
Data memory	>20 years (No motion – power off)
Fieldbus	EtherCAT®
Supply	10 ÷ 30 Vdc
	Protection against polarity reversal
Power consumption	2.5 W
Accuracy	± ½ LSB
Connection	2 M12 female connectors
	+1 M12 male connector
Interference immunity	EN 61000-6-2
Emitted interference	EN61000-6-4

▶ MECHANICAL	. & ENVIRONMENTAL SPE	CIFICATIONS

Model:	520 - 540 - 620	440 - 450	
Materials: housing / shaft	Aluminium / Stainless steel		
Weight	500 g ca		
Shaft/hollow shaft Ø (mm)	6, 8, 10	8, 10, 12, 14, 15	
Revolutions/minute	6000		
Starting torque	≤ 0.8 Ncm		
Intertia	≤ 25 g cm ²		
Max load	80 N axial/100 N radial		
Vibrations resistance	100 m/sec ²		
(10÷2000 Hz)			
Shock (11 ms)	50 G		
Protection degree	IP67 – IP65 shaft	side	
Operating temperature	-30 ÷ 70°C		
Stocking temperature	-30 ÷ 85°C		

Ether CAT.

► MEM-BUS EtherCAT ENCODER PROFILE

► EtherCAT COMMUNICATION PROTOCOL

as I/O systems, drives, sensors and actuators.

MEM-BUS EtherCAT® encoders offer:

• Easy installation and maintainance

• Flexible work ranges progamming

Real Time communication

Flexible number of nodes

• Net topologies configuratioin Automatic slaves addressing

Based on the industrial Ethernet communication protocol, the **EtherCAT®**

interface is steady, flexible and fast, therefore particularly suitable for communication between control systems and peripheral devices, such

- Ref IEC61158-1-6 & IEC61784-2
- Device Profile CANopen over EtherCAT (CoE), CiA DS-406
- Physical Layer: EtherCAT 100Base-TX, Fast Ethernet, ISO/IEC 8802-3
- Output code: Binary
- Cycle time ≥ 1 ms
- Transmission rate 100 Mbit/s
- Transmission: CAT-5 cable, shielded (STP), ISO/IEC 11801

► SETTABLE PARAMETERS

- Counting direction
- Measuring steps per revolution Total measuring length in steps
- Preset value Speed resolution

▶ CONNECTIONS

Connectors IN and OUT

M12 female type, D code

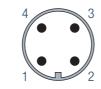
Pin	Signal
1	Tx +
2	Rx +
3	Tx -
4	Rx -

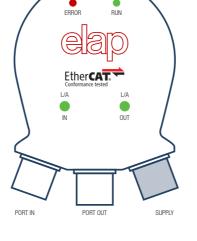


SUPPLY CONNECTOR

M12 male type, A code

Pin	Signal
1	Supply voltage (10 - 30 V DC)
2	N.C.
3	GND (0V)
1	NC

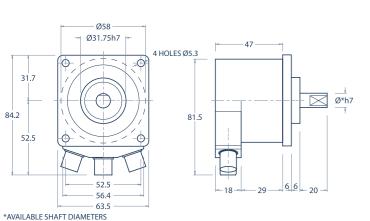




► COMMUNICATION MODES

MEM-BUS EtherCAT supports different operating modes:

- Free-Run: The slave application is not synchronized to EtherCAT. The local cycle is started by the local timer interrupt of the application controller. The cycle time can be modified by the Master, but this is a local cycle and it does not depend on communication and on Master cycle.
- SM3 Event: The slave application is synchronized to the SM3 Event (that is the cyclic inputs transmission to the Master). SM events are based on the time an EtherCAT frame is received. This time can jitter in the range of a few microseconds due to the EtherCAT Master implementation (delay in stack, PHY & MAC delay, etc.).
- DC: The slave application is synchronized to the SYNCO event, which is based on the Distributed Clocks Unit (DC). The jitter can be reduced to a few nanoseconds.
- The DC mode grants high real-time performances

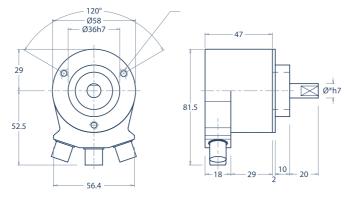


52.5 *AVAILABLE SHAFT DIAMETERS

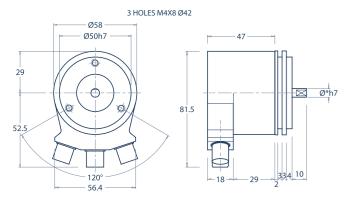
8 - 10 length 20mm 6 length 10mm

► MEM440-BUS

► MEM540-BUS



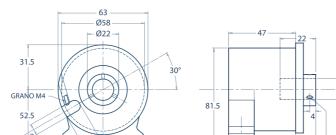




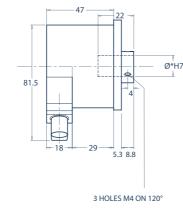
*AVAILABLE SHAFT DIAMETERS 8 - 10 length 20mm 6 length 10mm

► MEM620-BUS

8 - 10 length 20mm 6 length 10mm



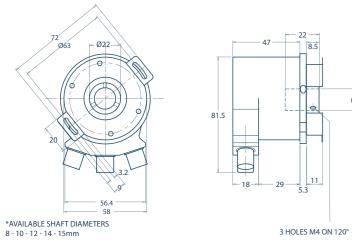
*AVAILABLE SHAFT DIAMETERS



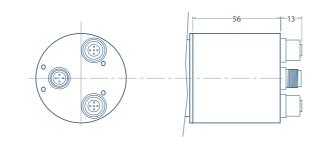
rif. M1551B

ref. M2162

► MEM-BUS WITH AXIAL CONNECTORS ► MEM450-BUS



VERSION WITH AXIAL CONNECTORS. REAR VIEW.







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