TWK_ ELEKTRONIK

High resolution absolute single-turn rotary encoder Model HBE

Document no.: HBE 13321 EE

Date: 13.01.2016



- Robust design for rough applications with high resolution requirement such as crane technology, construction machines and special engineering
- High vibration and shock resistance thanks to the compact mechanical design
- Resolution < 22 bit/360°
- Protection type IP 66



Design

- Robust housing (wall thickness 5 mm) manufactured from seawater-proof aluminium (AlMgSi1) or stainless steel (material: 1.4305 optionally 1.4404) - stainless steel shaft and ball bearing - magnetic based sensor system.
- Supply voltage with transient filtering, output driver unit forms the electrical interface SSI.
- Electrical connection via M12X1 connector, pin, 8-pin, A-coded

Function

The absolute angle information derived by the encoder is converted into serial information by an internal parallel-serial converter and then transmitted to a receiving electronic circuit in synchronism with a clock.

Important advantages are: Low number of data lines and high reliability.

An exhaustive description is contained in TWK's $\underline{\text{SSI }10630}$ pamphlet.



Technical data

Electrical data

Operating voltage:
 9 to 36 VDC (protected against polarity reversal)

■ Power consumption: < 1.8 W

Resolution: 16 bit (for higher resolution, plase contact our technical staff)

Code path: CW* or CCW** can be set
 Reference value: 0 to (total number of steps -1)
 Accuracy: ≤ ± 0.05 % (with reference to 360°)
 Reproducibility: ≤ ± 0.01 % (with reference to 360°)

■ Temperature drift: < 0.1 % (with reference to 360° over the entire temperature range)

■ SSI- interface: Regarding <u>SSI10630</u> (TWK)
■ Serial output SSI: Differential data output

(RS 422)

■ Clock input SSI: Differential data input

(RS 422)

■ Monoflop time: 16 ±10 µs (standard)

■ Clock rate: Max. 1 MHz

■ Connecting cable: Use twisted pair cable wit shield e.g. LiyCY 4x2x0.14 mm², shielded

Mechanical data

Operating speed: 500 rpm
 Angular acceleration: 10⁵ rad/s² max.
 Moment of inertia (rotor): 20 gcm²
 Operating torque: ≤ 2 Ncm
 Starting torque: ≤ 3 Ncm

Perm. shaft load: 250 N axially, 250 N radially
 Bearing service life: ≥ 10⁹ revolutions ***
 Weight: Aluminium approx. 0.4 kg, stainless steel approx. 0.6 kg

*) CW = increasing signal clockwise viewed looking towards the shaft

CCW = increasing signal counter-clockwise viewed looking towards the shaft

***) This value applies at maximum shaft load.



Technical data

Environmental data

■ Operating temperature range: - 40 °C to + 85 °C

■ Storage temperature range: - 40 °C to + 100 °C (without packaging)

Resistance

 $\ \square$ To shock: 250 m/s²; 6 ms

DIN EN 60068-2-27

 \Box To vibration: 200 m/s²;10 Hz ... 2000 Hz

DIN EN 60068-2-6

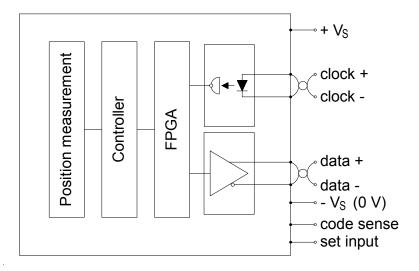
■ EMC standards: DIN EN 61 000 - 6 - 2 Immission (burst/ESD/etc.)

DIN EN 61 000 - 6 - 4 Emission

■ Protection type (DIN EN 60529): IP 66

(For higher protection types up to IP 69K, please contact our technical staff)

Principle circuit diagram

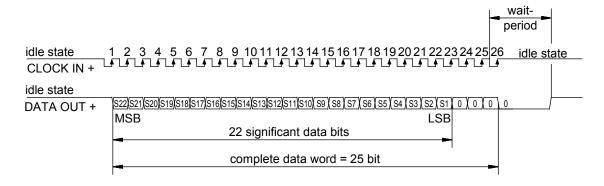


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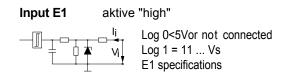
Data format

Interface profile SSI - 25 Bit



Input circuit E1

Input circuit for setting the reference value and for setting of the Code sense CW/CCW of the encoder.





Electrical connections, mating connector

Electrical connection

- Connector M12x1, pin, 8-pin, A-coded
- Refer to the tables below for the connection assignments; these are also enclosed with the devices.

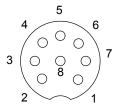
Mating connectors (to be ordered separately)

All of the mating connectors listed in the following table are M12X1, 8-pin, A-coded, with screw clamp connection, with protection type IP 67, with screening on the housing and the maximum connection cross-section is 0.5 mm².

Order number	Contact design	Connector design	Housing material	Cable Ø (mm)
STK8GS54	Socket	Straight	Nickel-plated brass	6 - 8
STK8WS86	Socket	Angled	Nickel-plated brass	6 -8
STK8GS105	Socket	Straight	Stainless steel	5.5 – 8.6

Please note: if angled mating connectors are used, please notify us so that the device connectors can be aligned accordingly.

Mating connector M12x1 pin diagrams (view of insertion side)



8-pin socket, A-coded

Pin connection assignment

Contact No.	Assigned with						
1	+ Vs = 9 36 V / Io >90 mA (typ. Io = 70 mA)						
2	- Vs = 0 VDC						
3	Clock in+ differential-clock input (opto-coupler) for peripheral driver acc. to specification of RS 42						
4	Clock in- differential-data driver accordingto specification of RS 422 standard						
5	Data out+						
6	Data out -						
7	SET input (input circuit E1) - Set zero point SET inactivated at Vi = Log 0 or not connected SET activated at Vi = Log 1						
8	Code sense CW at Vi = Log 0 or not connected CCW at Vi = Log 1						



Order number

HBE	58	- K	Α	65,536	R	S	Е	01	
									Electrical and mechanical variants*
								01	Standard
								Outp	out:
							Ε	SSI	
							Ele	ctrical	I connection:
									nector (bus in/bus out)
									=length in m
						Out	put (code	
						Bina		ode	
					Res	soluti	ion:		
				1 to	ste	os/3	360°		
				4,063,232					
			Housing material:						
				Aluminium					
			S	Stainless ste	el				
			Flange type:						
	58	K	Clamped flange, shaft 10 mm with flattened area						
		KF KP	Clamped flange, shaft 10 mm with feather key Clamped flange, shaft for measurement gear ZRS						
		KZ							
		S							
		ST		nchro flange, s				th flat	ttened area
		SR							2 mm (torque support, see accessories)
									2 mm with groove for feather key (torque support, see accessories)
	65	S	Syr	nchro flange, s	haft	12 n	nm		
	Design form								
	Model:								
	BE With SSI interface								
and are	a are documented in the factory.								

Accessories (to be ordered separately)

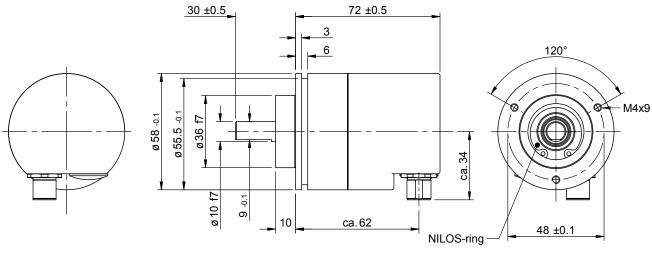
- Fastening clamps for sensor assembly KL 66-2-S See data sheet MZ 10111
- Play-free clamping coupling for shaft connection **KK14N** With groove for feather key according to DIN 6885 sheet 1 JS9, see data sheet KK 12301
- Torque support/stator coupling for shaft offset compensation between the rotary encoder and drive
 ZMS58 Manufactured from permanently elastic plastic, see data sheet <u>ZMS 12939</u>
- Please refer to the table on page 5 for the mating connector order numbers.

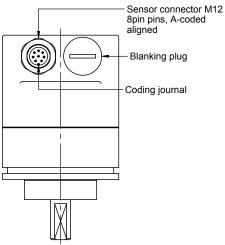


Installation drawing

Standard design form: clamped flange and shaft ø 10 mm with glattened area

Order number: HBE58 - KA 65536 R S E01 (see drawing)



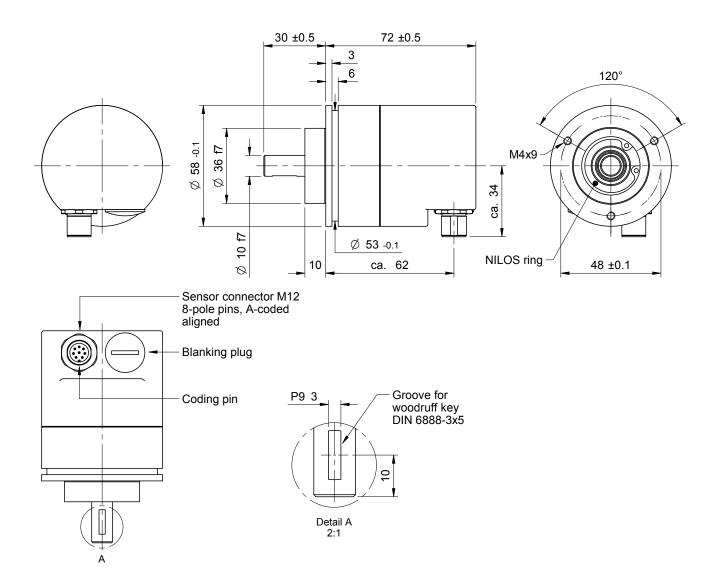




Installation drawing

Further possible design form: clamped flange, shaft 10 mm with woodruff key

Order number: HBE58 - KFA 65,536 R S E01

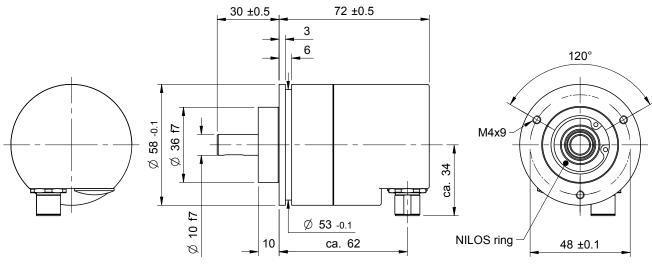


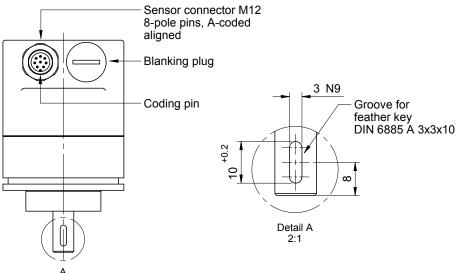


Installation drawing

Further possible design form: clamped flange, shaft 10 mm with feather key

Order number: HBE58 - KPA 65,536 R S E01





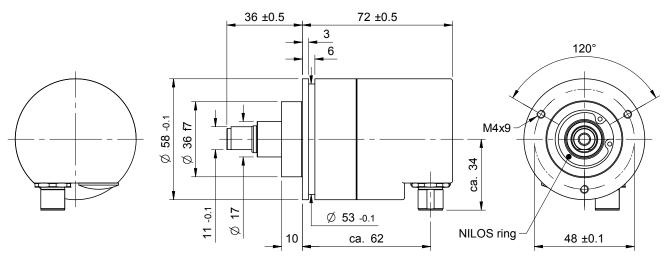


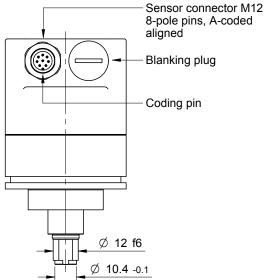
Installation drawing

Further possible design form: clamped flange, shaft for play compensating toothed gear ZRS

(toothed gear, see accessories)

Order number: HBE58 - KZA 65,536 R S E01



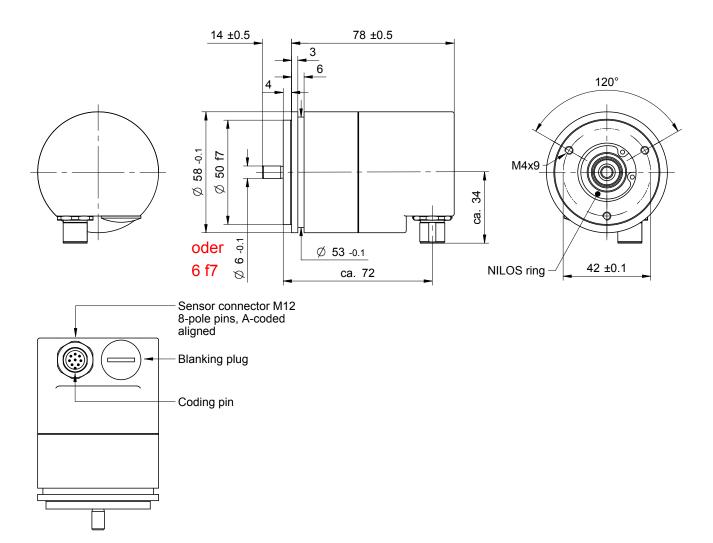




Installation drawing

Further possible design form: synchro flange, shaft 6 mm with flattened area

Order number: HBE58 - STA 65,536 R S E01

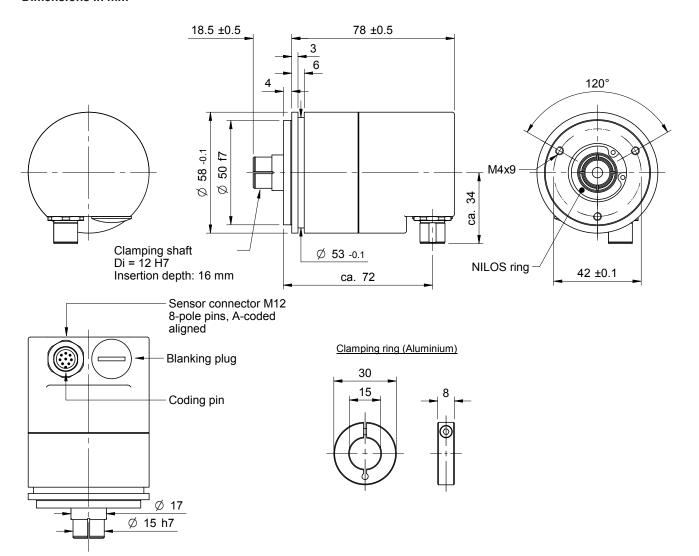




Installation drawing

Further possible design form: synchro flange, clamped shaft for 12 mm (torque support, see accessories)

Order number: HBE58 - SRA 65,536 R S E01



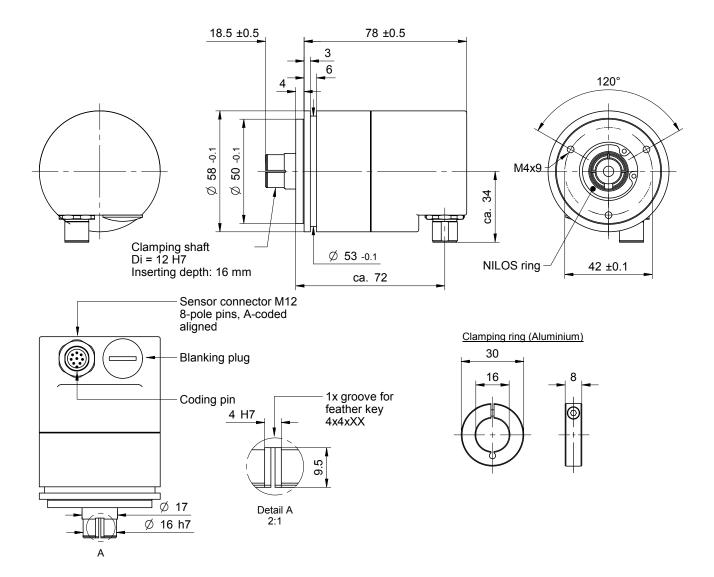


Installation drawing

Further possible design form: synchro flange, clamped shaft for 12 mm with groove for feather key

(torque support, see accessories)

Order number: HBE58 - SNA 65,536 R S E01





Installation drawing

Further possible design form: synchro flange, shaft 12 mm

Order number: HBE65 - SA 65,536 R S E01

